

Overview

Spatial pyramid models:

- Codebooks based on appearance only
- Location accounted for by spatial pooling in the spatial pyramid bins

Spatially local coding:

- Codebooks based on appearance and location
- No complicated pooling stage
- Uses linear SVM

We move responsibility for spatial locality to the coding phase.

Method	Appearance locality	Spatial locality
Bag-of-features	Coding	-
Spatial pyramid [1]	Coding	Pooling
Sparse coding SPM [2]	Sparse coding	Pooling
LLC [3]	Local coding	Pooling
"Ask-the-locals" [4]	Sparse coding + Pooling	Pooling
Spatially local coding	Coding	Coding

Simply add weighted location dimensions to each descriptor.

$$\phi_{\mathbf{i}}^{(\lambda)} = [\phi_{i1}, \phi_{i2}, \dots, \phi_{id}, \lambda x_i, \lambda y_i]$$

Features are pooled as in bag-of-words.

Learned features





Spatially Local Coding for Object Recognition

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Classification performance

Original SPM [1] **Original SPM (our** Localized soft assignment [6] Localized soft assignment (ours Sparse coding SPI Sparse coding SP SLC [8182d x 4] SLC [16384d x 4]

LLC (HOG) [3] Localized soft assignment (SIFT SLC [8192d x 4] SLC [16384d x 4] SLC [32768d x 4]

Boureau et al. [4] SLC [32768d x 4] SLC [65536d x 4]

SLC [65536d x 4]

References

CVPR (2006)

[2] Yang, J., Yu, K., Gon, Y., Huang, T.: Linear spatial pyramid matching using sparse coding for image classification. In: CVPR.

[3] Wang, J., Yang, J., Yu, K., Lv, F., Huang, T., Gong, Y.: Localityconstrained linear coding for image classification. In: CVPR. (2010)

[4] Boureau, Y.L., Le Roux, N., Bach, F., Ponce, J., LeCun, Y.: Ask the locals: multi-way local pooling for image recognition. In: ICCV. (2011)

[5] Muja, M., Lowe, D.: Fast approximate nearest neighbors with automatic algorithm configuration. In: VISSAPP. (2009)

In: ICCV. (2011)

[7] Boureau, Y.L., Bach, F., LeCun, Y., Ponce, J.: Learning mid-level features for recognition. In: CVPR. (2010)

	Cal. 101 (15)	Cal. 101 (30)	Cal. 256 (30)	
Single-scale SIFT features				
	EX	tracted every 8 pl	xeis	
	56.4	64.6 ± 0.8	-	
ırs)	57.8 ± 0.3	65.2 ± 0.4	30.0 ± 0.4	
	-	74.21 ± 0.81	-	
s)	66.2 ± 0.4	72.2 ± 0.3	37.2 ± 0.2	
, PM [3]	67.0 ± 0.45	73.2 ± 0.54	34.02 ± 0.35	
PM [7]	-	71.8 ± 1.0	-	
	68.4 ± 0.2	75.5 ± 0.4	38.9 ± 0.3	
	68.3 ± 0.3	75.7 ± 0.4	40.0 ± 0.2	
Multi-scale features				
Extracted every 8 pixels				
	65.43	73.44	41.19	
) [6]	-	76.58 ± 0.71	-	
	71.4 ± 0.4	78.0 ± 0.4	41.8 ± 0.3	
	72.5 ± 0.3	79.2 ± 0.2	43.4 ± 0.2	
	70.9 ± 0.4	77.2 ± 0.6	44.3 ± 0.1	
Single-scale SIFT features				
Extracted every 4 pixels				
	-	77.3 ± 0.6	41.7 ± 0.8	
	71.6 ± 0.4	79.6 ± 0.8	44.6 ± 0.2	
	-	-	45.1 ± 0.2	
Multi-scale SIFT features Extracted every 4 pixels				
	72.7 ± 0.4	81.0 ± 0.2	46.6 ± 0.2	

[1] Lazebnik, S., Schmid, C., Ponce, J.: Beyond Bags of Features: Spatial Pyramid Matching for Recognizing Natural Scene Categories.

[6] Liu, L., Wang, L., Liu, X.: In Defense of Soft-assignment Coding.